

Robust a-posteriori analysis of the (1D) advection-diffusion-reaction problems

Giancarlo Sangalli

sangalli@imati.cnr.it



Via Ferrata, 1

27100 Pavia (Italy)

1st LNCC Meeting on Computational Modelling

Petrópolis, Brazil

August 9–13, 2004

A-posteriori estimates (adaptivity) \leftrightarrow multiscale

- adaptivity is effective for capturing localized small-scales
- Araya R. and Valentin F., “A Multiscale A Posteriori Error Estimate”, to appear in CMAME.
- Sangalli G., “A robust a posteriori estimator for the Residual-free Bubbles method applied to advection-diffusion problems”, Numer. Math., Vol. 89 (2), pp. 379-399, 2001.

Outline:

- one-dimensional adv.-diff.-reac. differential problem
- residual-based a-posteriori estimators known in literature
- robustness (symmetric vs. non-symmetric problem)
- construction of a new estimator (for a new norm of the error)
- numerical tests

We consider the very simple 1D advection-diffusion-reaction problem:

$$\mathcal{L}u := -\varepsilon u'' + \beta u' + \rho u = f \text{ in } (0, 1), \quad u(0) = u(1) = 0.$$

Introducing the bilinear form $a(w, v) := {}_{H^{-1}} \langle \mathcal{L}w, v \rangle_{H_0^1}$, $\forall w, v \in V$, we have the variational formulation: find $u_h \in V$ such that:

$$a(u, v) = \langle f, v \rangle, \forall v \in V;$$

and the *standard* and *stabilized* FEM:

1) Standard FEM: Find $u_h \in V_h \in V$ (...piecewise polynomials) s.t.:

$$a(u_h, v_h) = \langle f, v_h \rangle, \forall v_h \in V_h;$$

2) SUPG: Find $u_h \in V_h \in V$ such that, given $\tau_T \approx h/|\beta|$:

$$a(u_h, v_h) + \sum_T \tau_T \int_T \mathcal{L}u_h \beta v_h' = \langle f, v_h \rangle + \sum_T \tau_T \int_T f \beta v_h', \quad \forall v_h \in V_h,$$

1 Residual-based a posteriori estimators

An a posteriori estimator is an expression $\eta(f, u_h)$ which estimates the numerical error $\|u - u_h\|$. It is reliable and efficient when the

$$\text{e.i.} = \text{effectivity index} := \frac{\eta(f, u_h)}{\|u - u_h\|}$$

is close to 1. It is called *robust* (in this context) when e.i. $\simeq 1$ uniformly with respect to the operator coefficients ε , β and ρ .

estimator for $\mathcal{L}w = -w''$

I. BABUŠKA AND A. MILLER, *A feedback finite element method with a posteriori error estimation. I. The finite element method and some basic properties of the a posteriori error estimator*, CMAME, 61 ('87)

↓

robust estimator for $\mathcal{L}w = -\varepsilon w'' + \rho w$

R. VERFÜRTH, *Robust a posteriori error estimators for a singularly perturbed reaction-diffusion equation*, Numer. Math., 78 ('98)

↓

non-robust estimator for $\mathcal{L}w = -\varepsilon w'' + \beta w' + \rho w$

R. VERFÜRTH, *A posteriori error estimators for convection-diffusion equations*, Numer. Math., 80 ('98), pp. 641–663

↓

the present quasi-robust estimator for $\mathcal{L}w = -\varepsilon w'' + \beta w' + \rho w$ (1D).

The loss of robustness is confirmed in numerical tests:

S. BERRONE, *Robustness in a posteriori error analysis for FEM flow models*, Numer. Math., 91 (2002), pp. 389–422.

V. JOHN, *A numerical study of a posteriori error estimators for convection-diffusion equations*, Comput. Methods Appl. Mech. Engrg., 190 (2000), pp. 757–781.

A. PAPASTAVROU AND R. VERFÜRTH, *A posteriori error estimators for stationary convection-diffusion problems: a computational comparison*, Comput. Methods Appl. Mech. Engrg., 189 (2000), pp. 449–462.

1.1 case $\mathcal{L}w = -w''$ (Babuska, Miller)

$$\begin{aligned} \|u - u_h\|_{H_0^1} &\stackrel{\boxed{1}}{\approx} \|f - \mathcal{L}u_h\|_{H^{-1}} \\ &\stackrel{\boxed{2}}{\approx} \left(\sum_T h_T^2 \|f - \mathcal{L}u_h\|_{L^2(T)}^2 \right)^{1/2} =: \eta \end{aligned}$$

$\boxed{1}$ because \mathcal{L} is an isometry: $\|w\|_{H_0^1} = \|\mathcal{L}w\|_{H^{-1}}$;

$\boxed{2}$ “ $\leq C$ ” for the Galerkin orthogonality

“ $\geq C$ ” because $f - \mathcal{L}u_h$ is “discrete”, assuming f piece-wise polynomial.

1.2 case $\mathcal{L}w = -\varepsilon w'' + \rho w$ (Verfürth 1998)

1 is ok with the *energy norm* $\|w\|_E = \left(\varepsilon |w|_{H_0^1}^2 + \rho \|w\|_{L^2}^2 \right)^{1/2}$, since

$$\|u - u_h\|_E \stackrel{\text{1}}{=} \|f - \mathcal{L}u_h\|_{E^*} := \sup_{v \in H_0^1} \frac{\langle f - \mathcal{L}u_h, v \rangle}{\|v\|_E};$$

2 this step is similar to the previous case, leading to

$$\|f - \mathcal{L}u_h\|_{E^*} \stackrel{\text{2}}{\approx} \left[\sum_T \min\{\rho^{-1}, \varepsilon^{-1} h_T^2\} \|f - \mathcal{L}u_h\|_{L^2(T)}^2 \right]^{1/2} + \left[\sum_z \min\{\rho^{-1/2} \varepsilon^{-1/2}, \varepsilon^{-1} h_z\} [\varepsilon u_h']^2(z) \right]^{1/2}$$

1.3 case $\mathcal{L}w = -\varepsilon w'' + \beta w' + \rho w$ (Verfürth 1998)

Now we have:

$$\begin{aligned}
 \|u - u_h\|_E &\stackrel{\boxed{1}}{\leq} \|f - \mathcal{L}u_h\|_{E^*} \\
 &\stackrel{\boxed{2}}{\approx} \left[\sum_T \min\{\rho^{-1}, \varepsilon^{-1} h_T^2\} \|f - \mathcal{L}u_h\|_{L^2(T)}^2 \right]^{1/2} \\
 &\quad + \left[\sum_z \min\{\rho^{-1/2} \varepsilon^{-1/2}, \varepsilon^{-1} h_z\} [\varepsilon u_h']^2(z) \right]^{1/2} =: \hat{\eta}_{old}
 \end{aligned}$$

1 this is no more an equivalence: indeed \mathcal{L} is coercive w.r.t. the energy norm $\|\cdot\|_E$ ($\Rightarrow \|w\|_E \leq \|\mathcal{L}w\|_{E^*}$) but is not continuous uniformly w.r.t. the coefficients ($\|\mathcal{L}w\|_{E^*} \not\leq C\|w\|_E$);

2 still ok.

if we want an estimator from below, then we need a different expression; the situation is

$$\check{\eta}_{old} \leq \|u - u_h\|_E \leq \hat{\eta}_{old},$$

where $\hat{\eta}_{old}/\check{\eta}_{old}$ depends on the coefficients.

The weak step in the previous estimate is $\boxed{1}$ where we used the energy norm:

$$\|u - u_h\|_E \stackrel{\boxed{1}}{\leq} \|f - \mathcal{L}u_h\|_{E^*},$$

we have to use instead a *natural* norm $\|\cdot\|_V$

$$\|u - u_h\|_V \stackrel{\boxed{1}}{\simeq} \|f - \mathcal{L}u_h\|_{V^*}.$$

2 Obtaining $\|w\|_V \simeq \|\mathcal{L}w\|_{V^*}$

The construction of a possible $\|\cdot\|_V$ has been addressed in:

G. SANGALLI, *A uniform analysis of non-symmetric and coercive linear operators*, Tech. Rep. 23-PV, I.M.A.T.I.-C.N.R., 2003.

Roughly speaking:

$$\mathcal{L}w = -\varepsilon w'' + \rho w \qquad \|w\|_E^2 = \varepsilon |w|_{H_0^1}^2 + \rho \|w\|_{L^2}^2$$

$$\mathcal{L}w = -\varepsilon w'' + \beta w' + \rho w \qquad \|w\|_V^2 = \varepsilon |w|_{H_0^1}^2 + |\beta| \cdot |w|_{1/2}^2 + \rho \|w\|_{L^2}^2.$$

Then we can reason as before, deriving

$$\|u - u_h\|_V \stackrel{\boxed{1}}{\simeq} \|f - \mathcal{L}u_h\|_{V^*}$$

$$\stackrel{\boxed{2}}{\simeq} \text{new a-posteriori estimator.}$$

$$\begin{aligned}
C_1 \check{\eta}_{new} &:= C_1 \left(\sum_T \check{\eta}_T^2 + \sum_z \check{\eta}_z^2 \right)^{1/2} \\
&\leq \|f - \mathcal{L}u_h\|_{V^*} \\
&\leq C_2 \left(\sum_T \hat{\eta}_T^2 + \sum_z \hat{\eta}_z^2 \right)^{1/2} =: C_2 \hat{\eta}_{new}.
\end{aligned}$$

$$\check{\eta}_T^2 = \min\{\rho^{-1}, \beta^{-1} h_T, \varepsilon^{-1} h_T^2\} \|f - \mathcal{L}u_h\|_{L^2(T)}^2$$

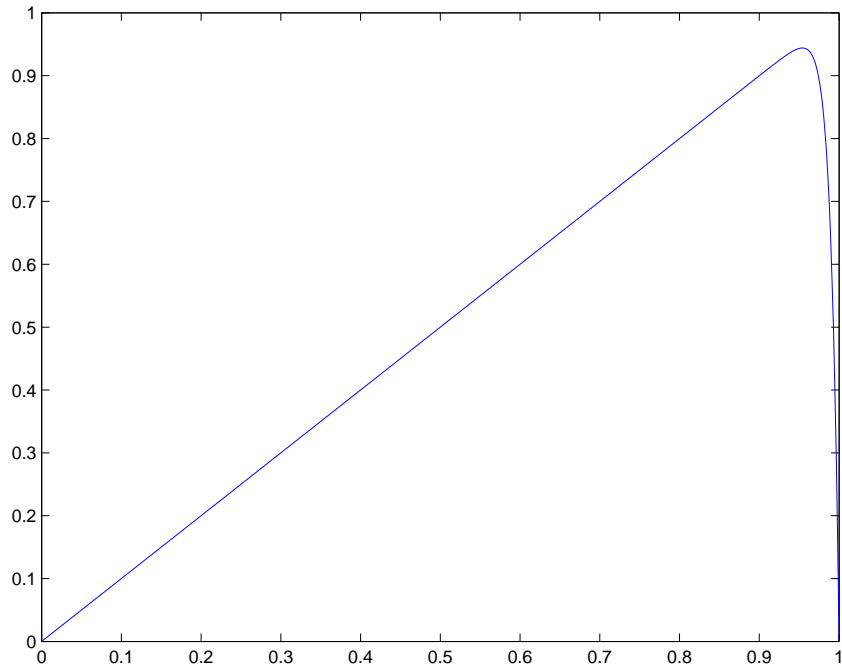
$$\check{\eta}_z^2 = \min\{\rho^{-1/2} \varepsilon^{-1/2}, \beta^{-1}, \varepsilon^{-1} h_T\} (\varepsilon [u'_h](z))^2$$

$$\hat{\eta}_T^2 = \min\{\rho^{-1}, \beta^{-1} (1 + \log(Pe)) h_T, \varepsilon^{-1} h_T^2\} \|f - \mathcal{L}u_h\|_{L^2(T)}^2$$

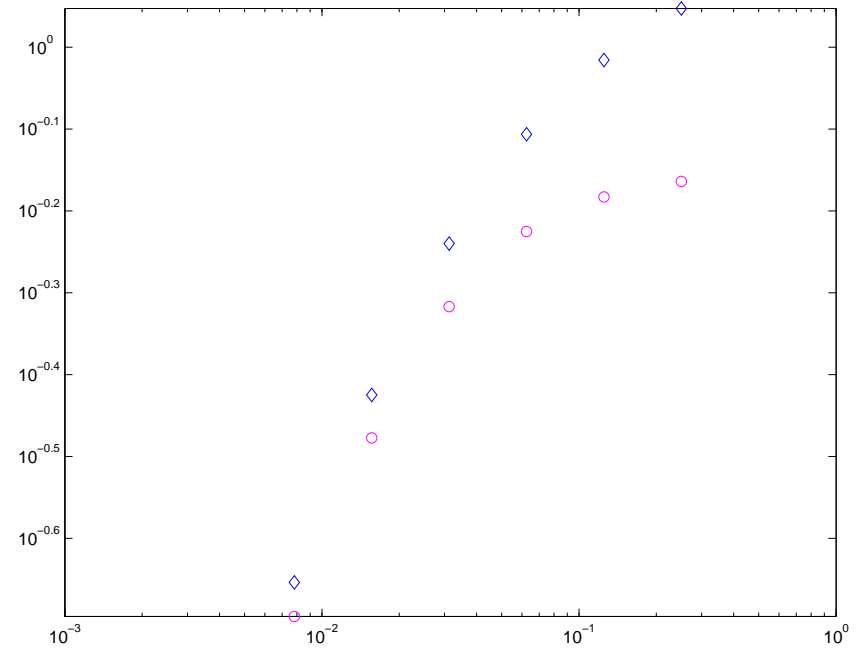
$$\hat{\eta}_z^2 = \min\{\rho^{-1/2} \varepsilon^{-1/2}, \beta^{-1} (1 + \log(Pe)), \varepsilon^{-1} h_T\} (\varepsilon [u'_h](z))^2$$

$$Pe := \frac{\text{diam}(\Omega) \|\beta\|}{\varepsilon}.$$

test n.1: no reaction

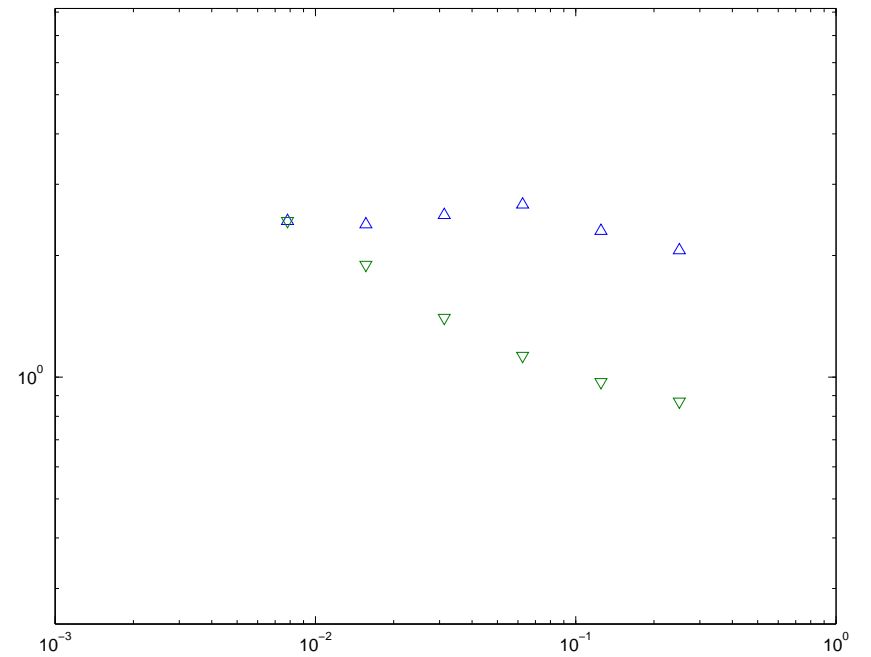
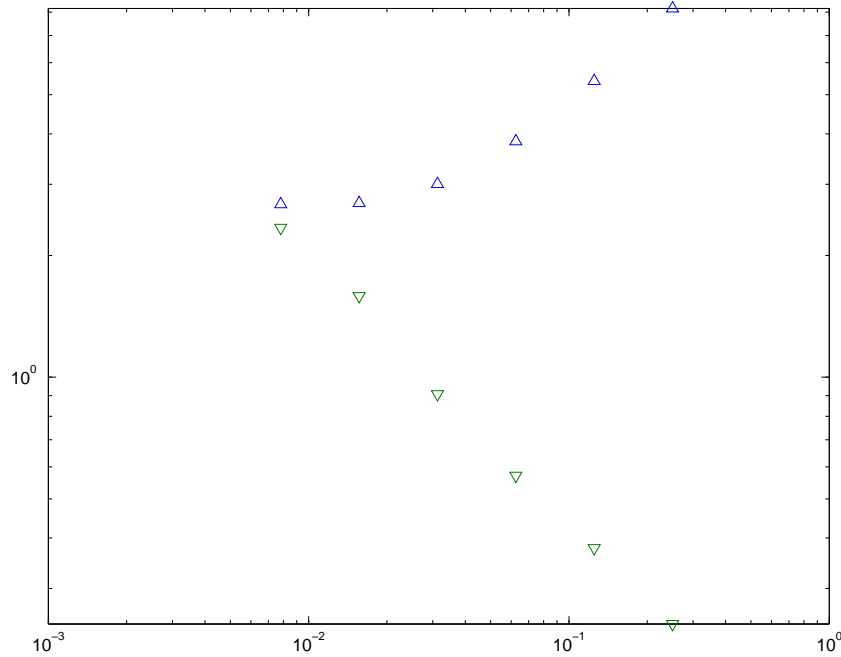


u for $\varepsilon = 10^{-2}$, $\beta = 1$ and $\rho = 0$.



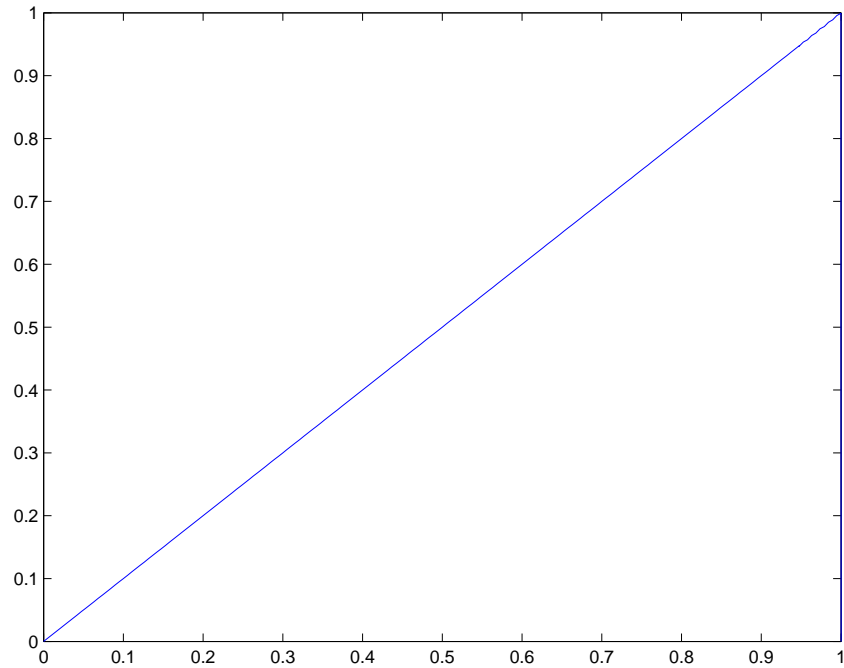
$\circ = \|u - u_h\|_E$ and $\diamond = \|u - u_h\|_V$ vs. h .

effectivity indexes for test n.1

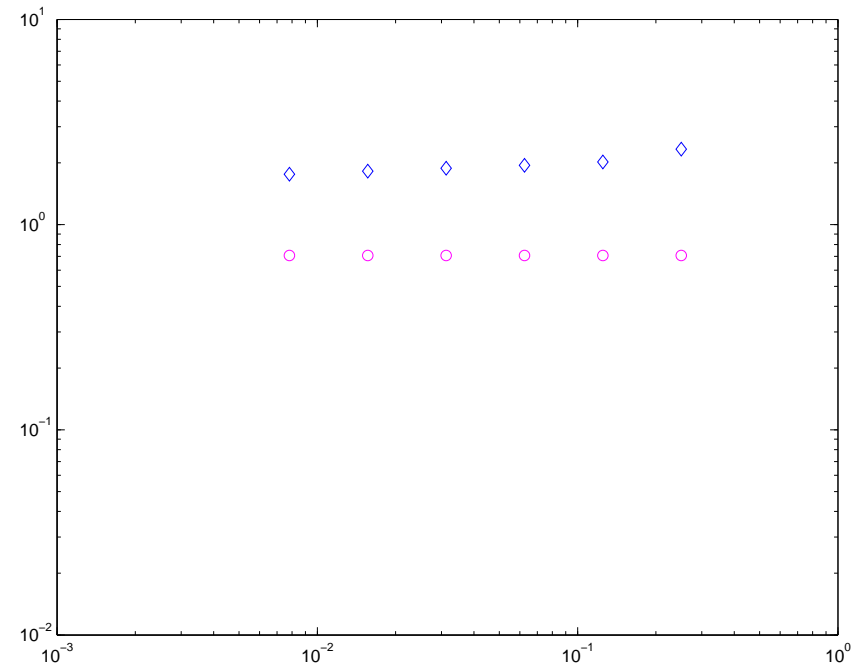


e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, vs. h ; ∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. h

test n.2: no reaction

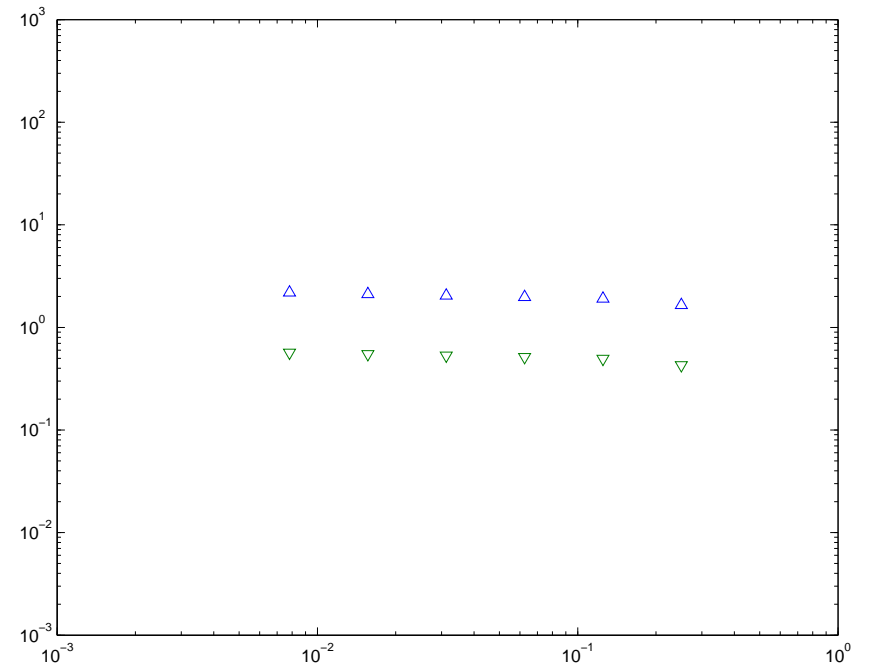
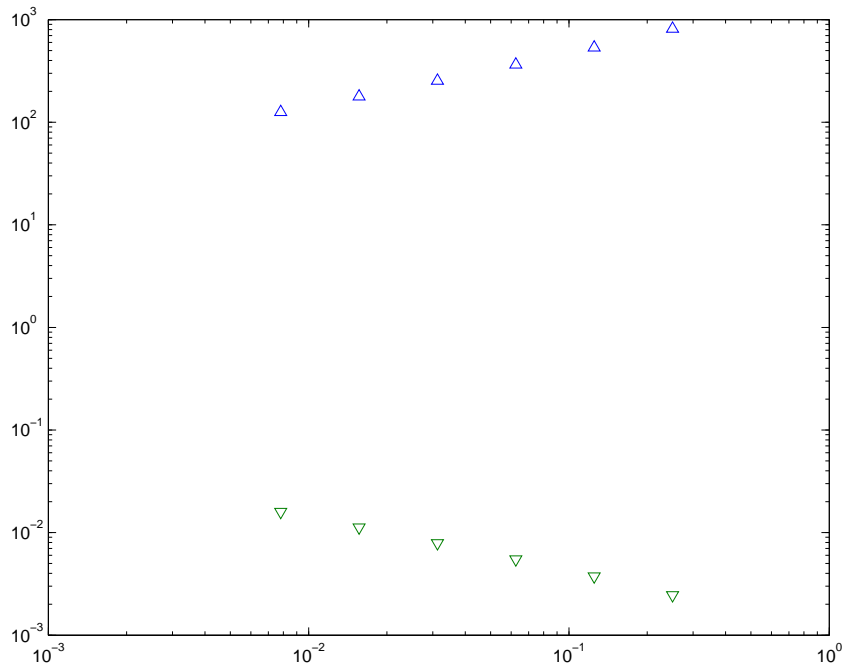


u for $\varepsilon = 10^{-6}$, $\beta = 1$ and $\rho = 0$.



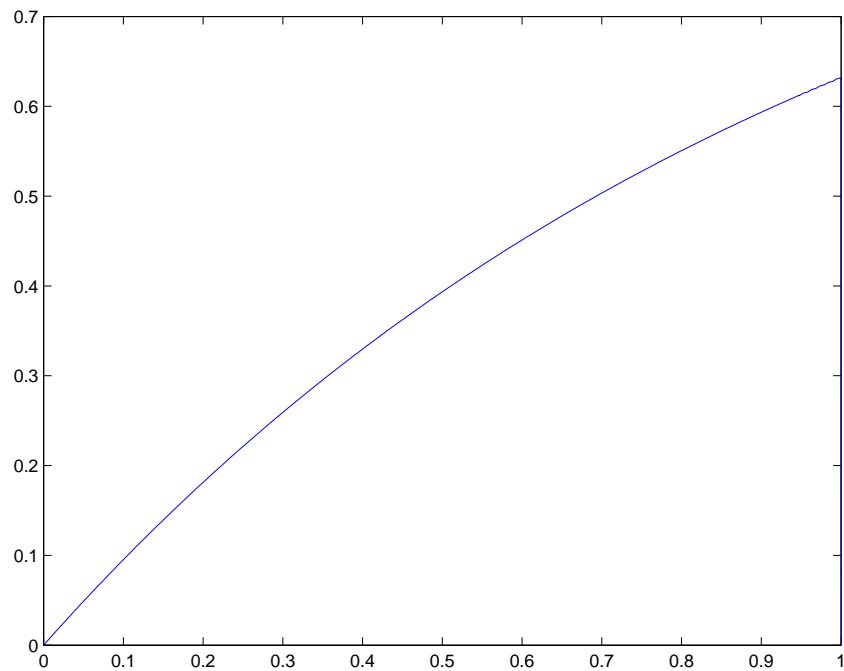
$\circ = \|u - u_h\|_E$, $\diamond = \|u - u_h\|_V$ vs. h .

effectivity indexes for test n.2

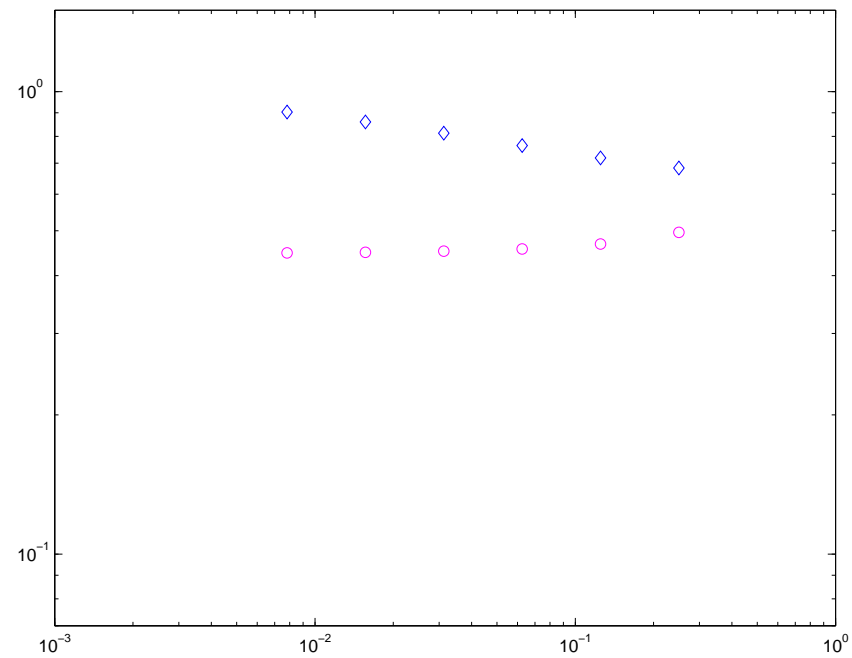


e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, vs. h ; ∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. h

test n.3: with reaction

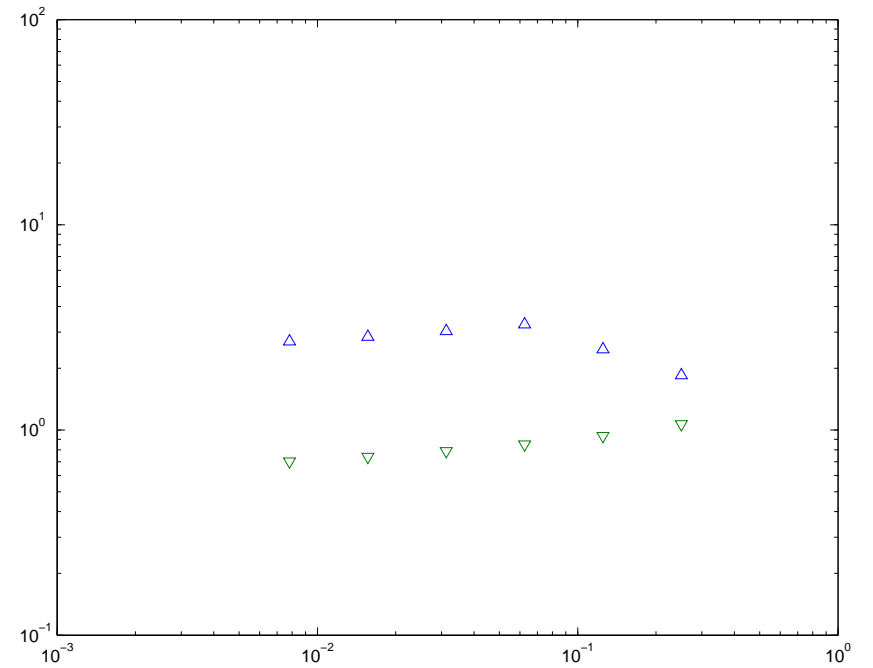
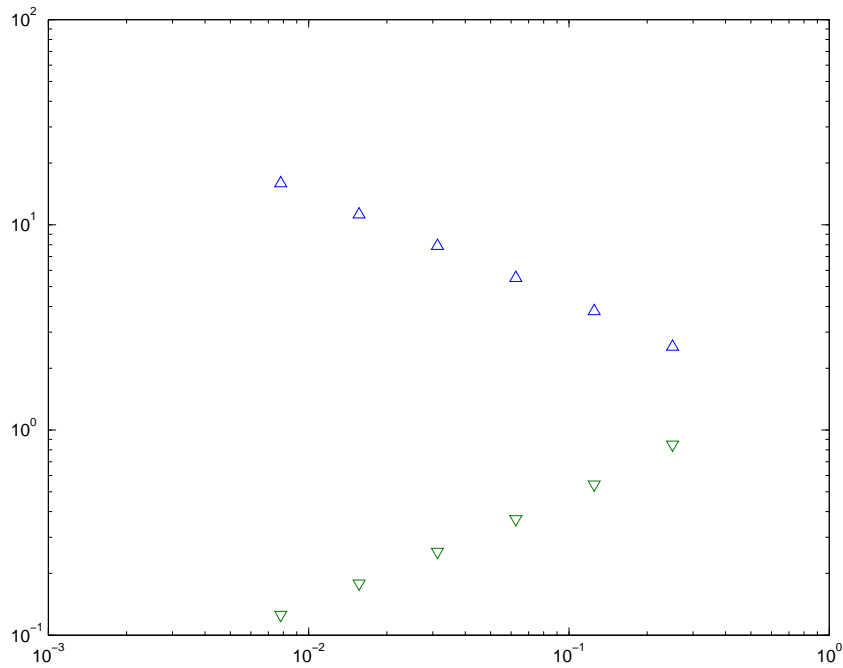


u for $\varepsilon = 10^{-6}$, $\beta = 1$ and $\rho = 1$.



$\circ = \|u - u_h\|_E$, $\diamond = \|u - u_h\|_V$, vs. h .

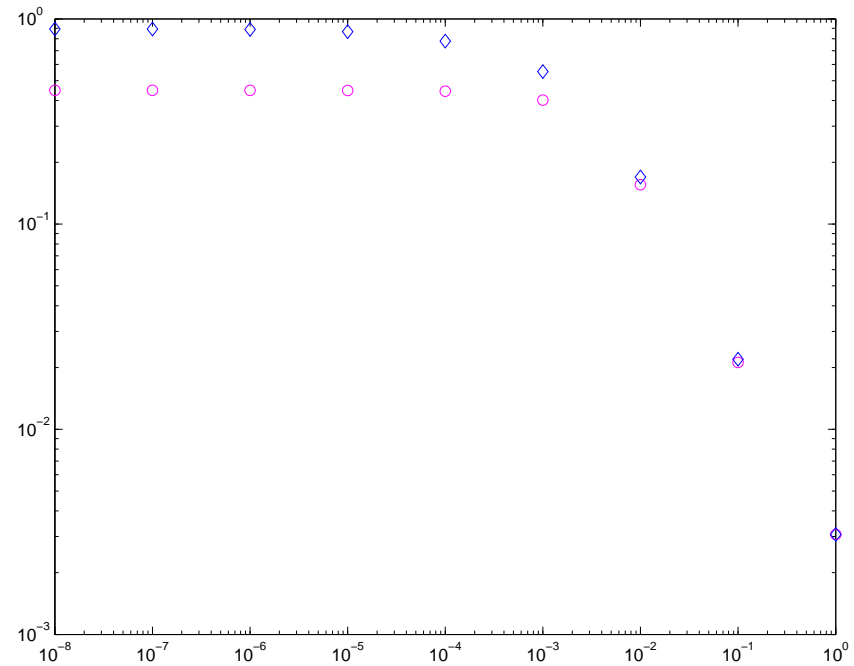
effectivity indexes for test n.3



e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, vs. h ; ∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. h

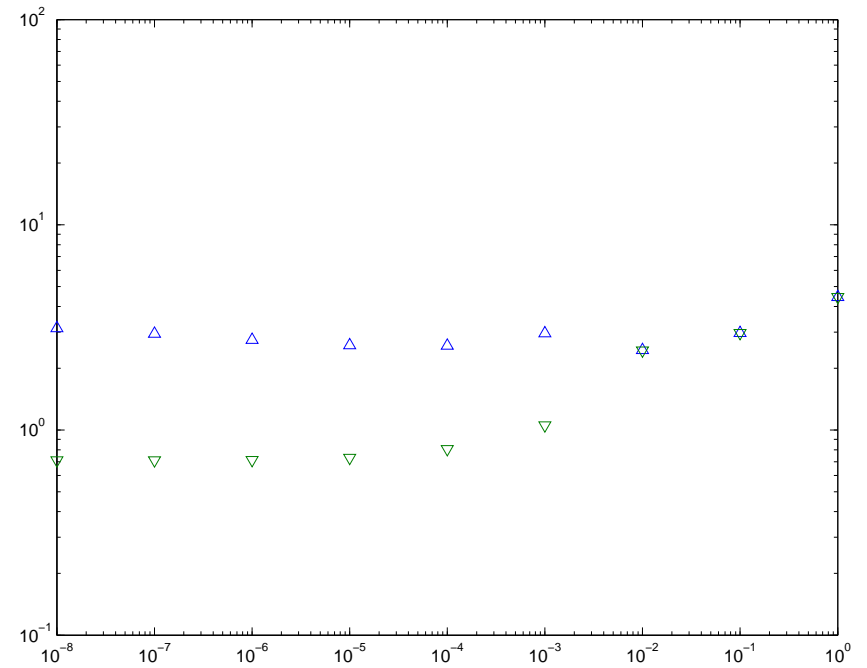
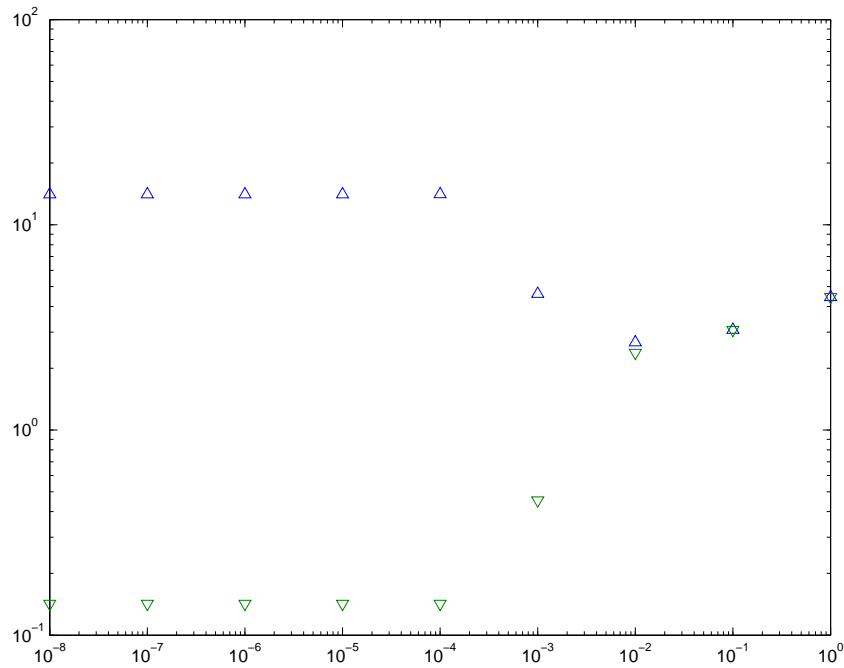
test n.4: varying ε

keep a fixed meshsize h
and let $\varepsilon \rightarrow 0$



$$\circ = \|u - u_h\|_E, \diamond = \|u - u_h\|_V, \text{ vs. } \varepsilon.$$

effectivity indexes for test n.4

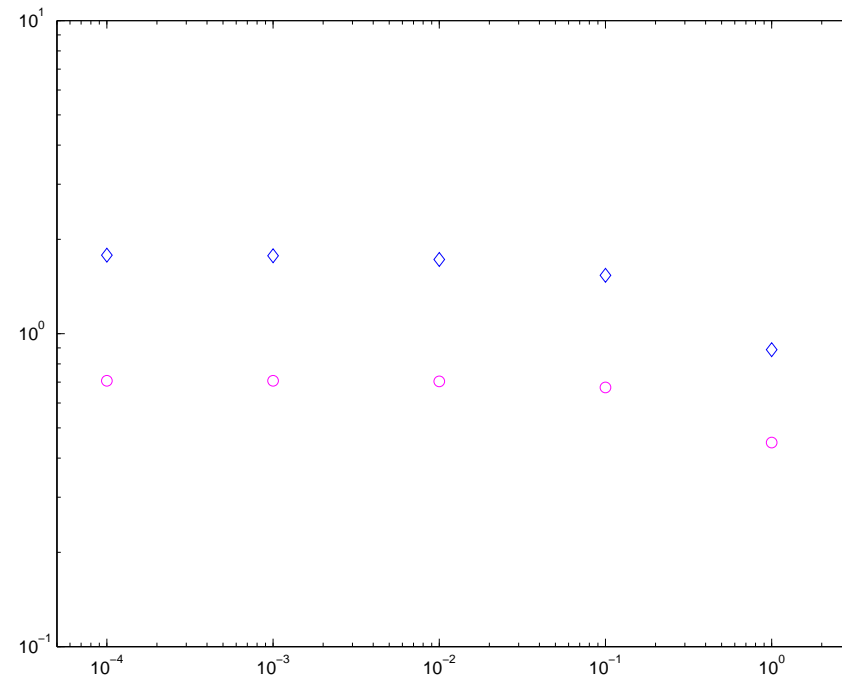


e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, ε ;

∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. ε .

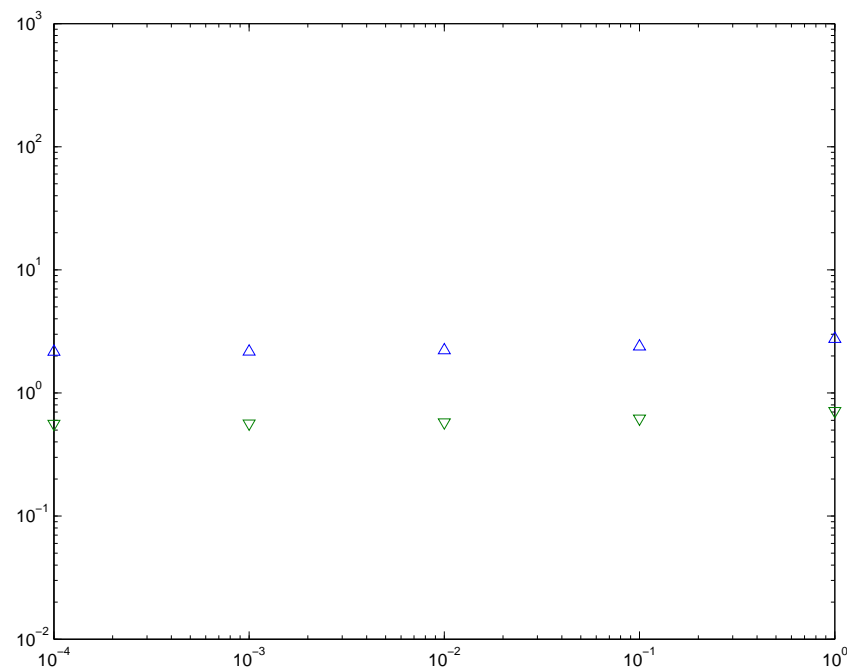
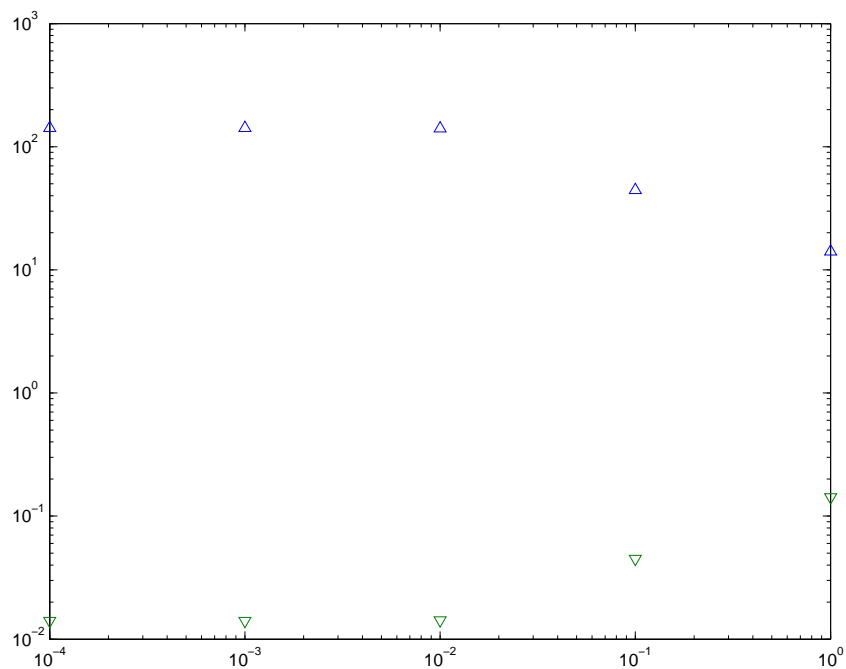
test n.5: varying ρ

keep a fixed meshsize h
and let $\rho \rightarrow 0$



$\circ = \|u - u_h\|_E$, $\diamond = \|u - u_h\|_V$, vs. ρ .

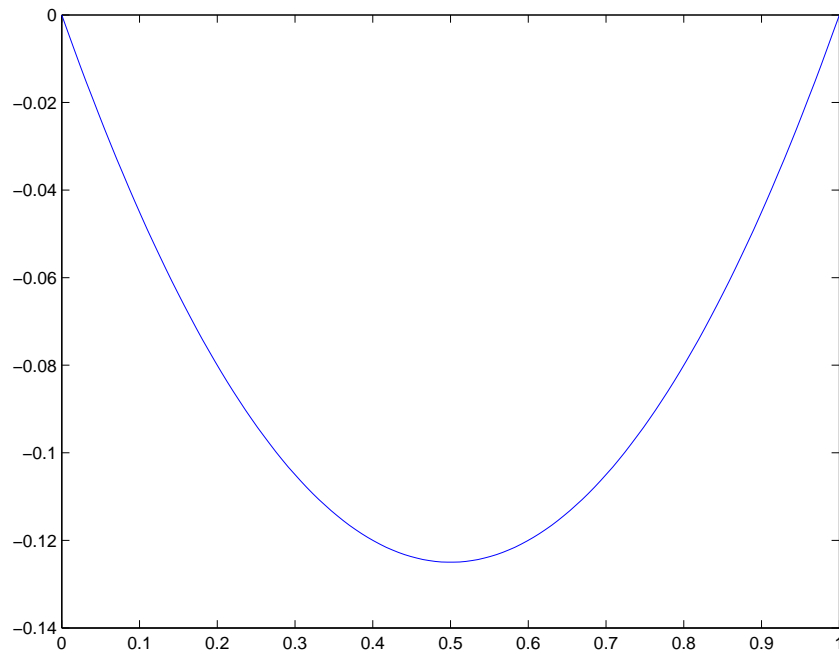
effectivity indexes for test n.5: varying ρ



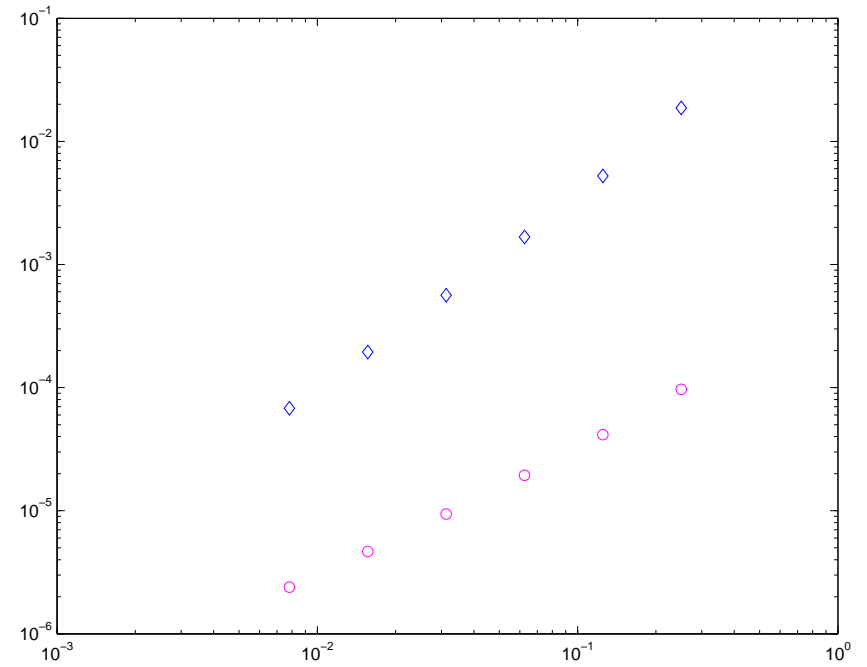
e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, ρ ;

∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. ρ .

test n.6: smooth u

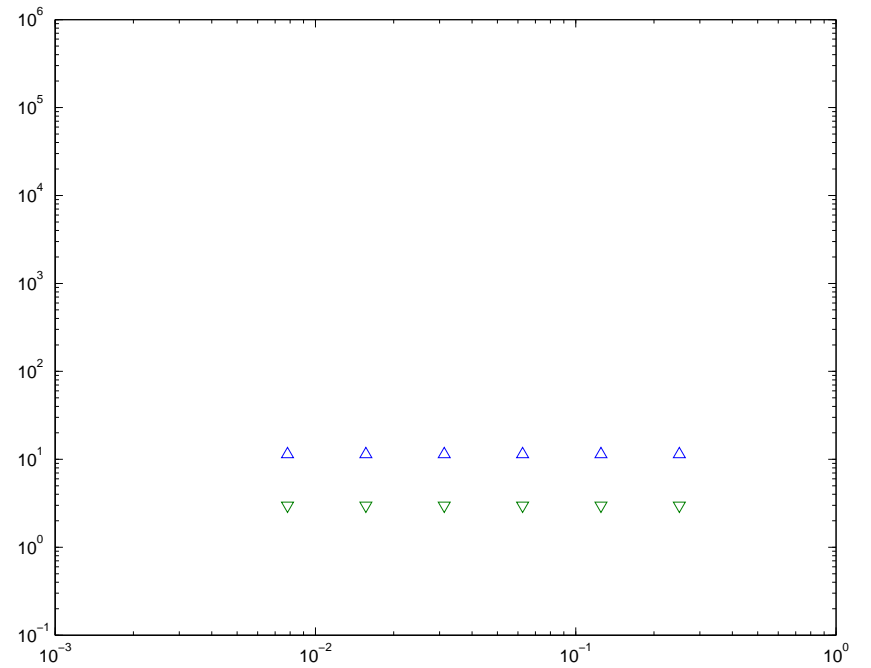
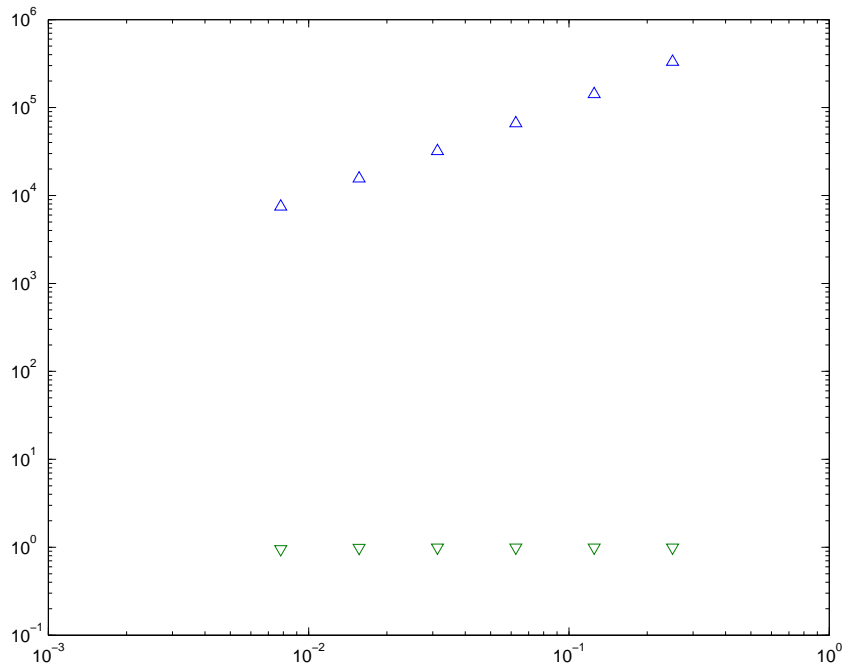


u for $\varepsilon = 10^{-6}$, $\beta = 1$ and $\rho = 0$.



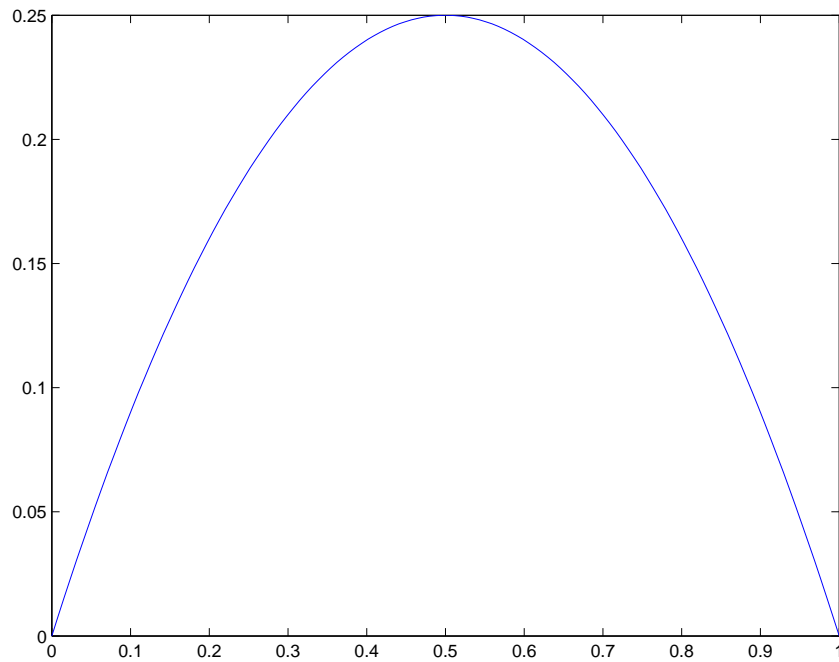
$\circ = \|u - u_h\|_E$, $\diamond = \|u - u_h\|_V$ vs. h .

effectivity indexes for test n.6

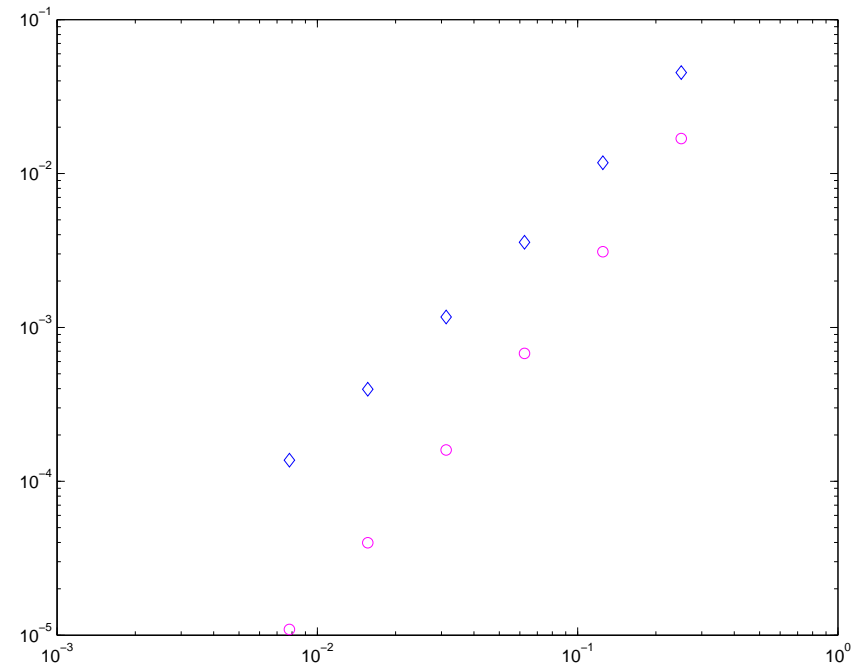


e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, vs. h ; ∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. h

test n.7: another smooth u ,

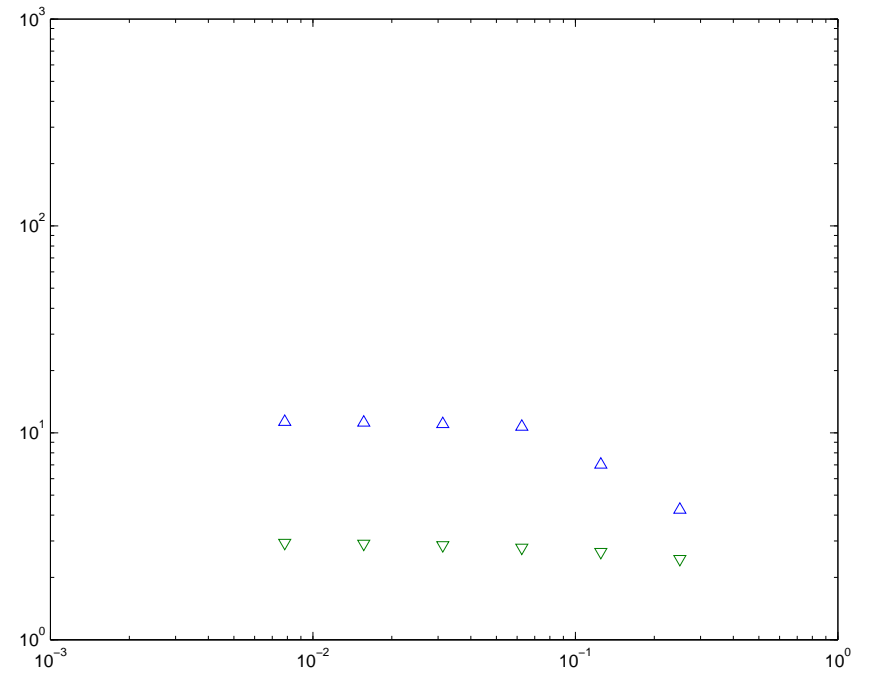
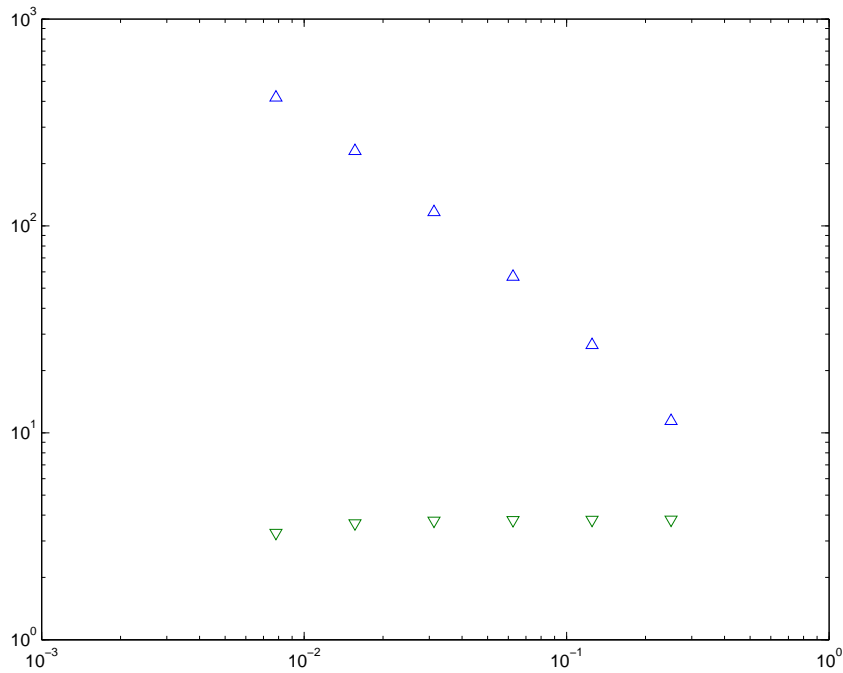


u for $\varepsilon = 10^{-6}$, $\beta = 1$ and $\rho = 1$.



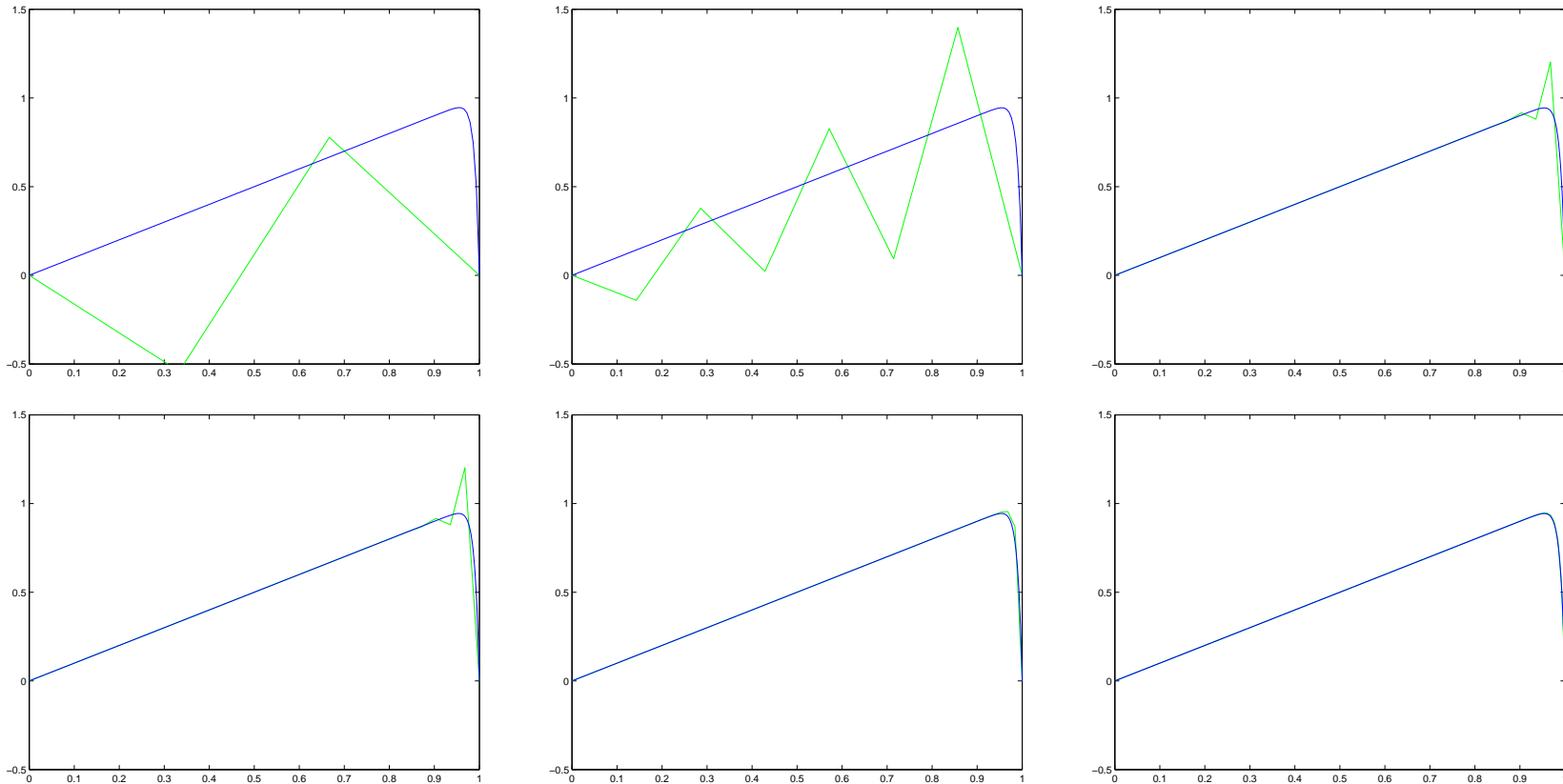
$\circ = \|u - u_h\|_E$, $\diamond = \|u - u_h\|_V$ vs. h .

effectivity indexes for test n.7



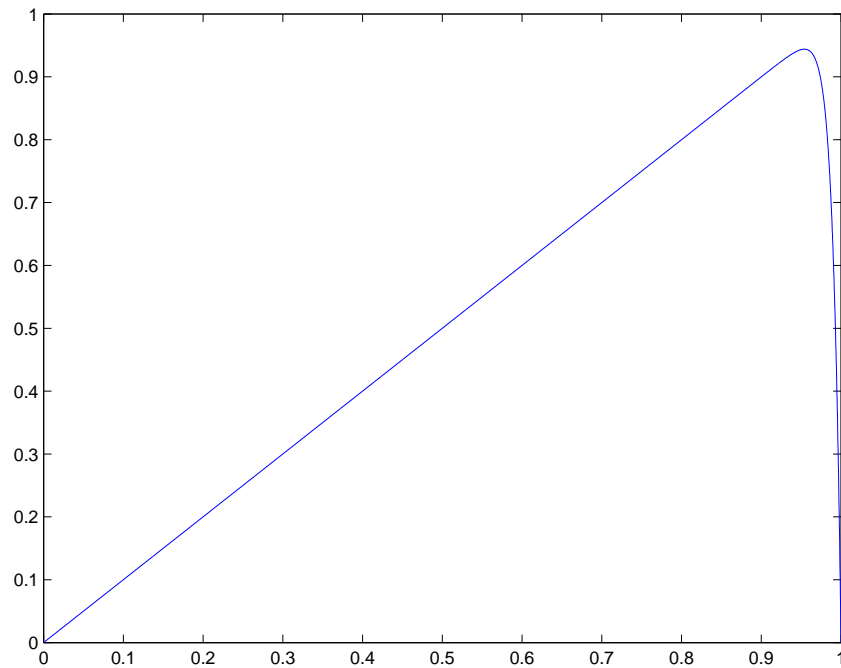
e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, vs. h ; ∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. h

test n.8: Standard Galerkin (unstable when $Pe_T := \beta h_T/\varepsilon > 1$)

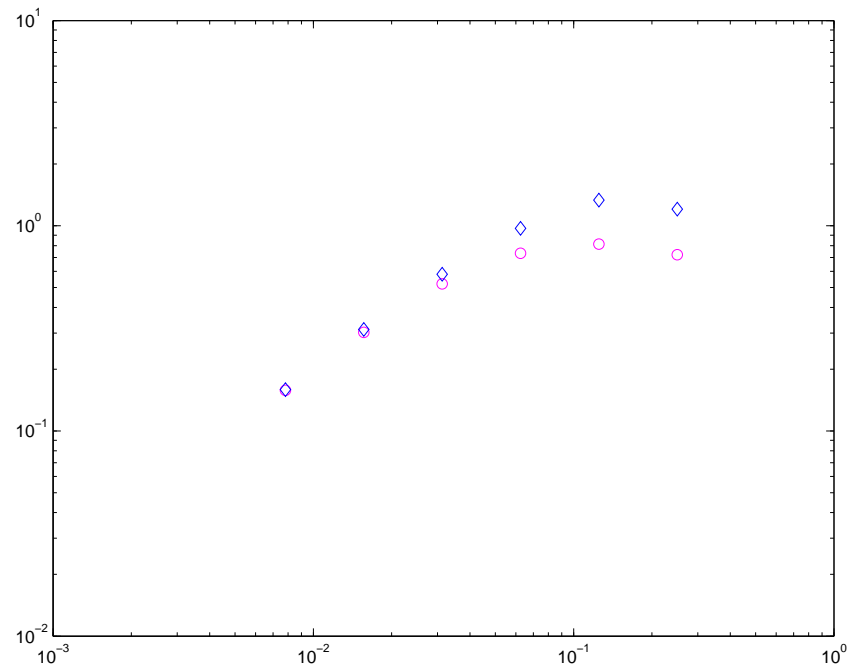


u and a sequence of discrete solutions u_h , for $\varepsilon = 10^{-2}$, $\beta = 1$, $\rho = 0$;

test n.8: Standard Galerkin (unstable when $Pe_T := \beta h_T / \varepsilon > 1$)

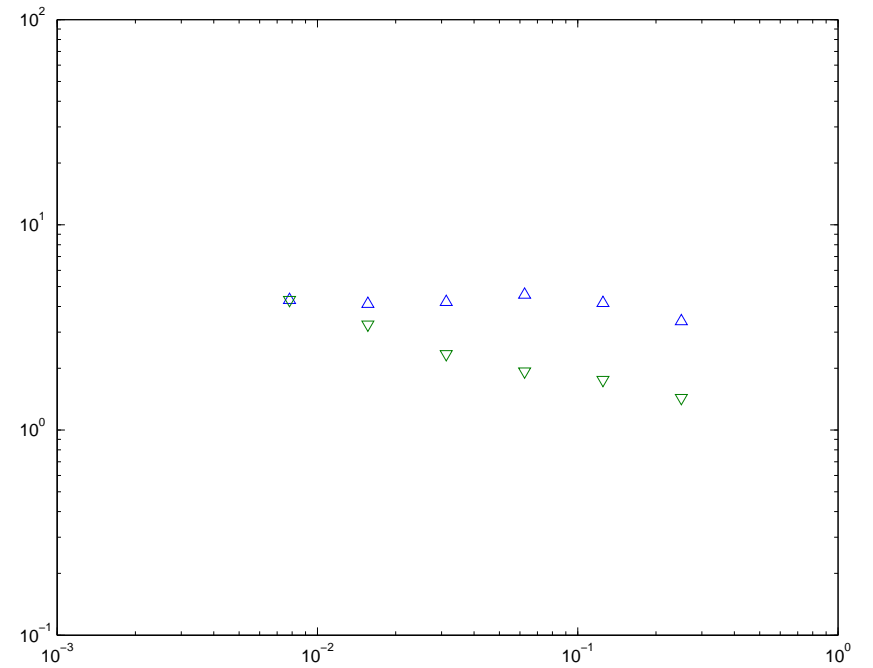
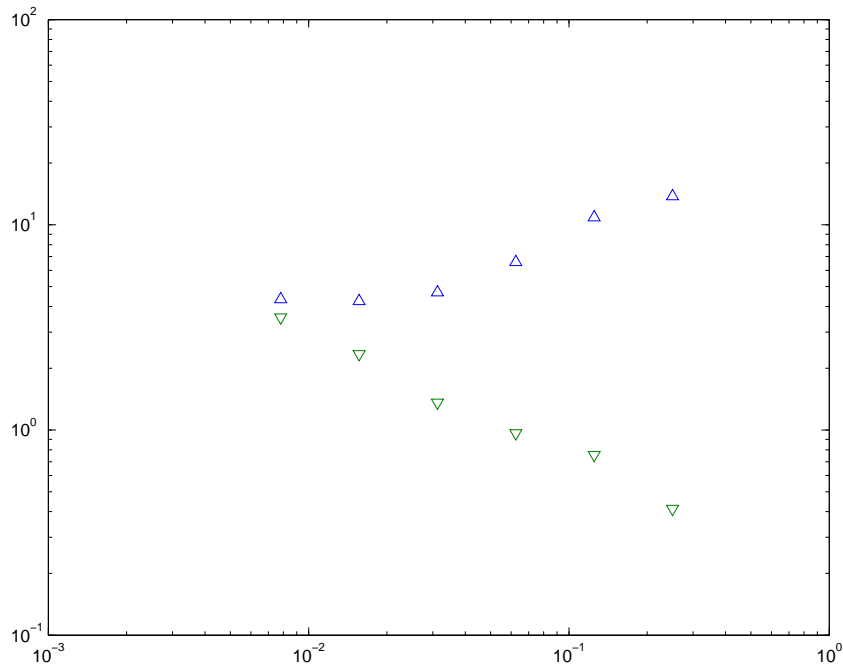


u for $\varepsilon = 10^{-2}$, $\beta = 1$, $\rho = 0$;



$\circ = \|u - u_h\|_E$, $\diamond = \|u - u_h\|_V$, vs. ρ .

effectivity indexes for test n.8

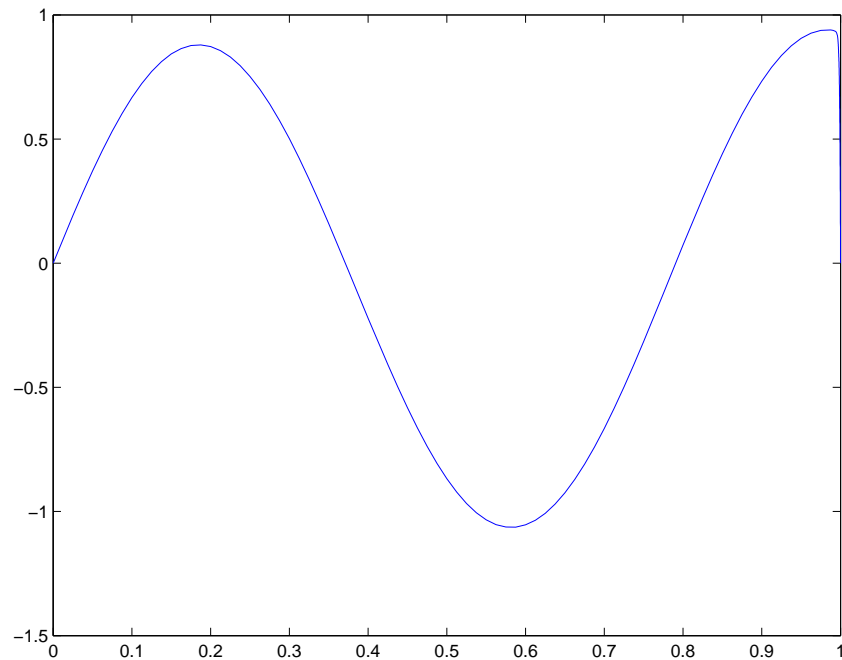


e.i.: ∇ for $\check{\eta}_{old}$ and \triangle for $\hat{\eta}_{old}$, vs. h ; ∇ for $\check{\eta}_{new}$ and \triangle for $\hat{\eta}_{new}$, vs. h

test n.9: first example of adaptivity

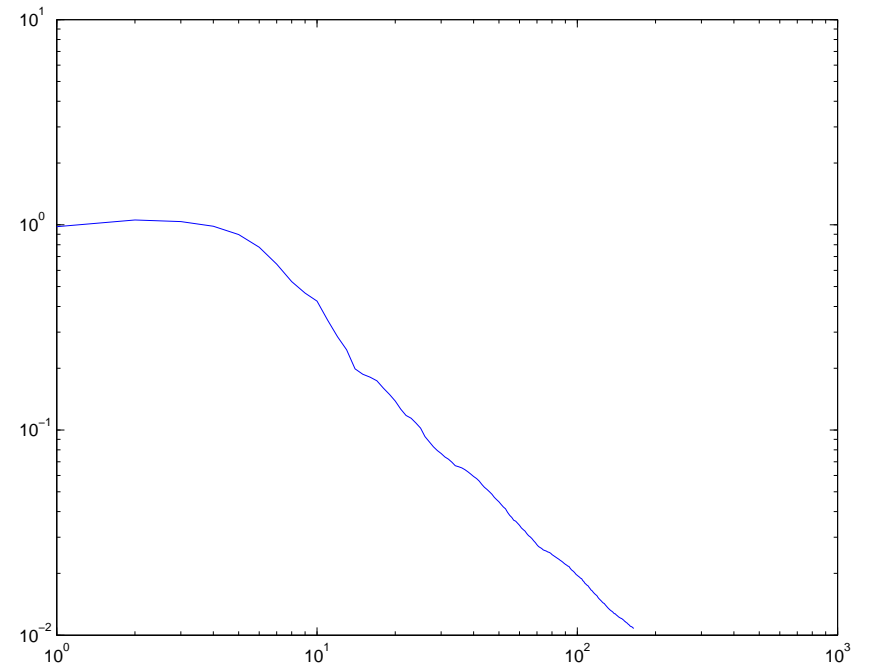
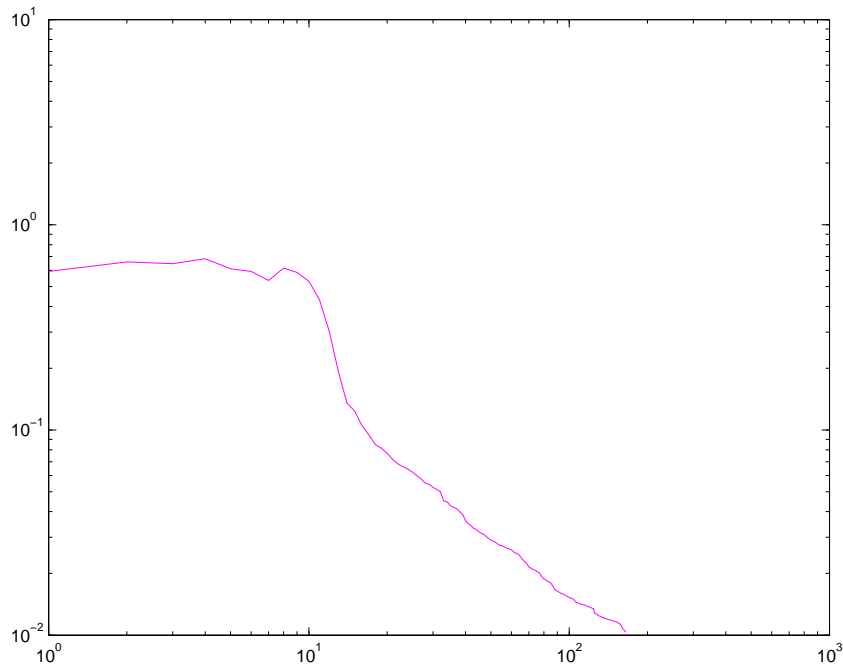
$$\varepsilon = 10^{-3}, \beta = 1, \rho = 1 \text{ and}$$
$$f(x) = \frac{5}{2}\pi \cos\left(\frac{5}{2}\pi x\right)$$

the adaptivity is driven by
the (local) estimator from
below.



the exact solution u .

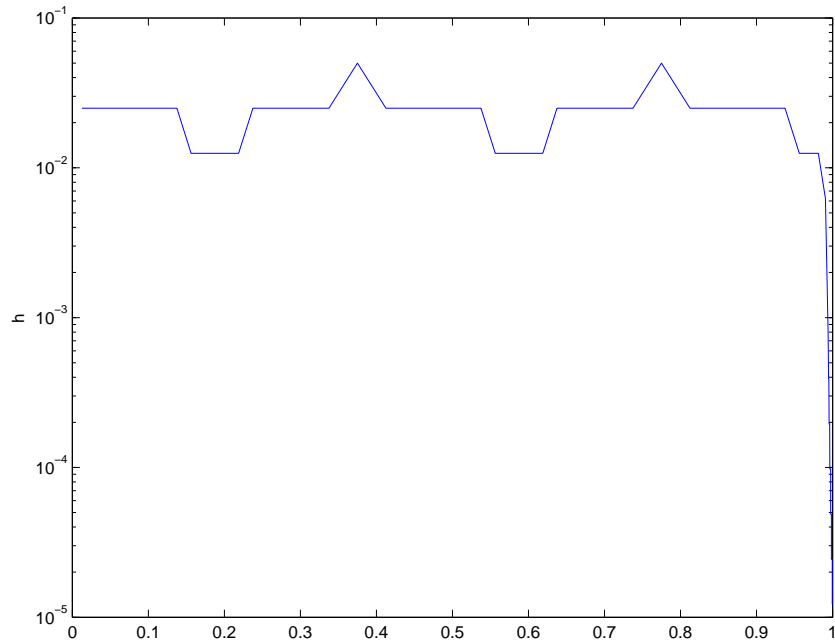
test n.9: error plots



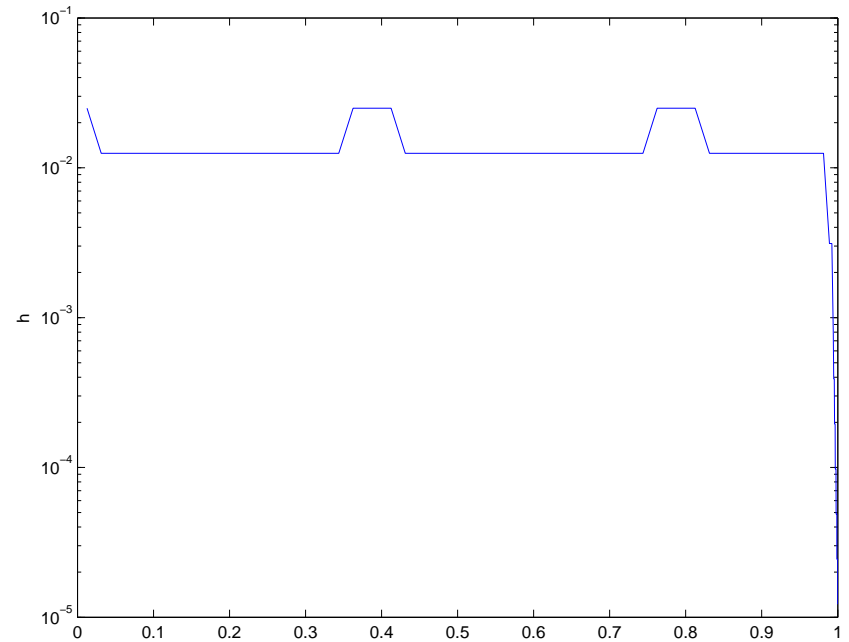
$\|u - u_h\|_E$ vs. the number of d.o.f.;

$\|u - u_h\|_V$, vs. the number of d.o.f..

test n.9: final meshes

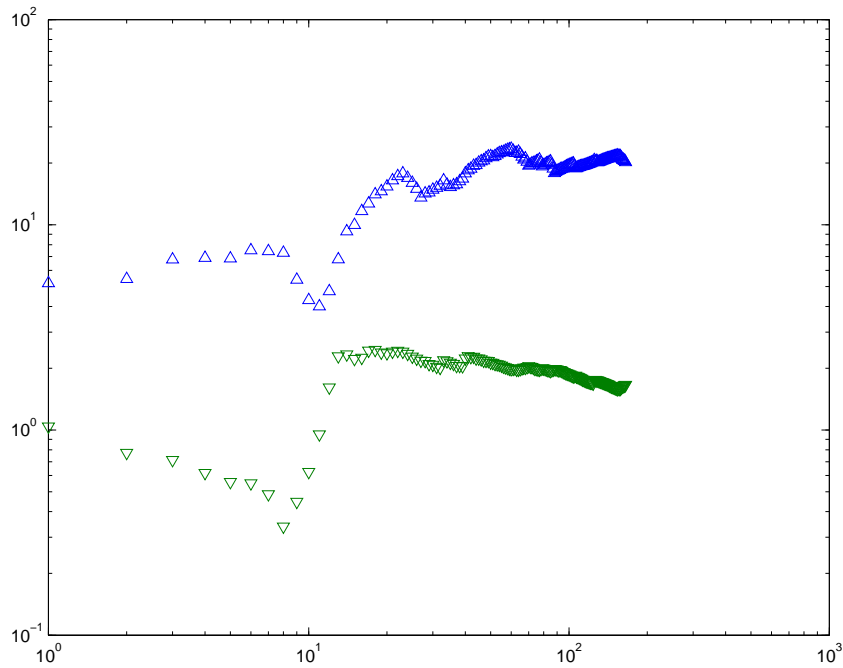


final mesh-sizes using $\check{\eta}_{old}$;

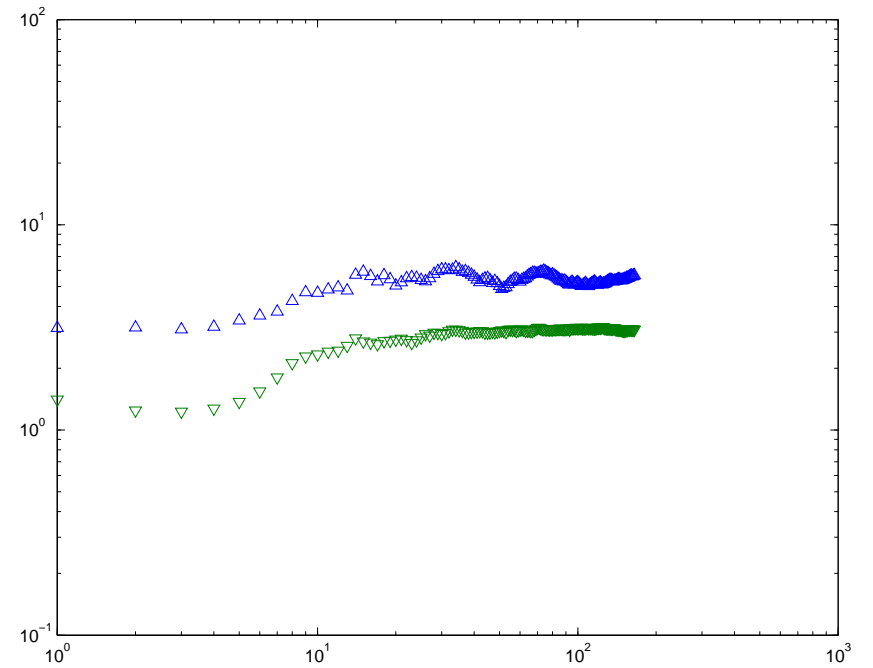


final mesh-sizes using $\check{\eta}_{new}$.

test n.9: effectivity indexes



e.i.: ∇ , $\check{\eta}_{old}$ and \triangle , $\hat{\eta}_{old}$, vs. # d.o.f.

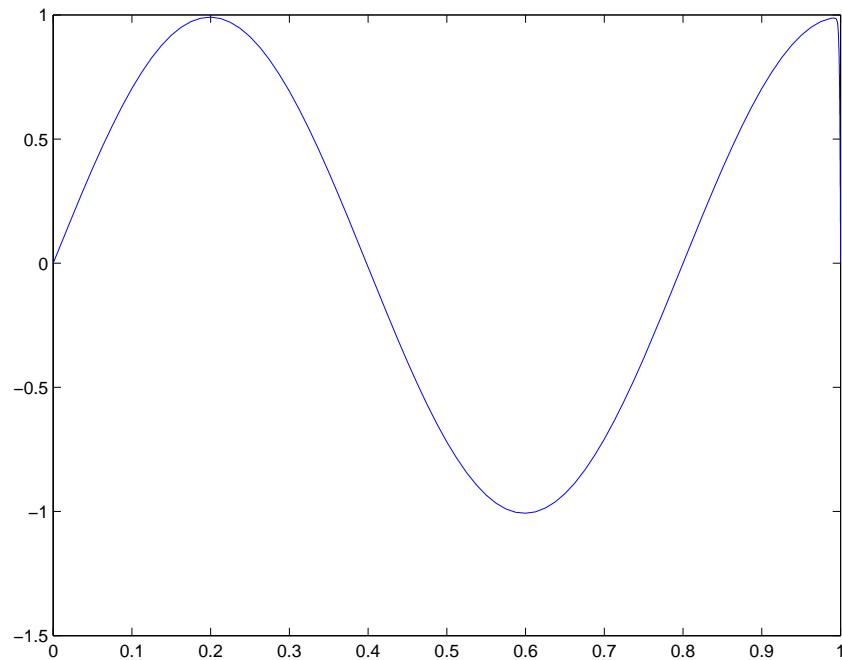


∇ , $\check{\eta}_{new}$ and \triangle , $\hat{\eta}_{new}$, vs. # d.o.f.

test n.10: second example of adaptivity

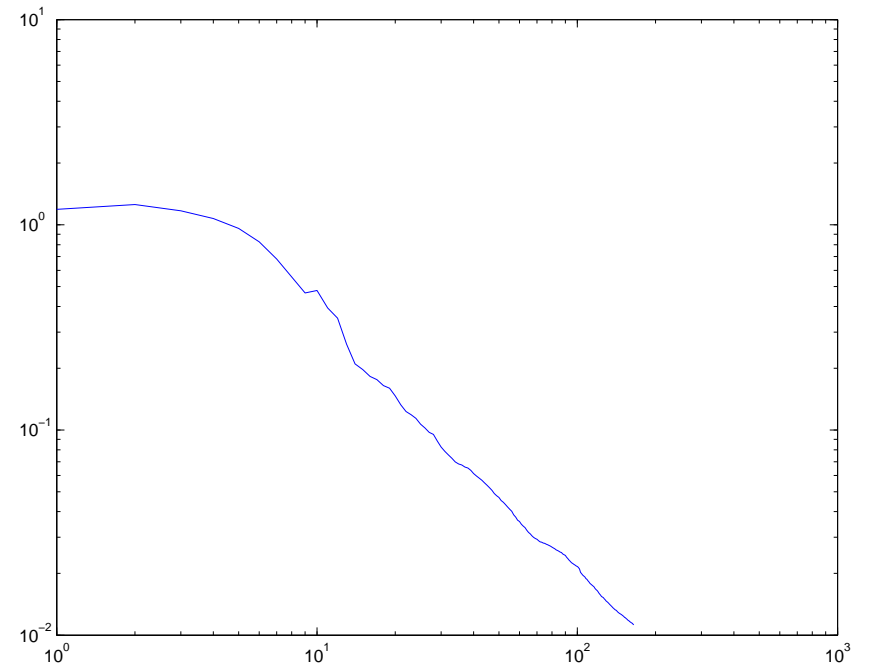
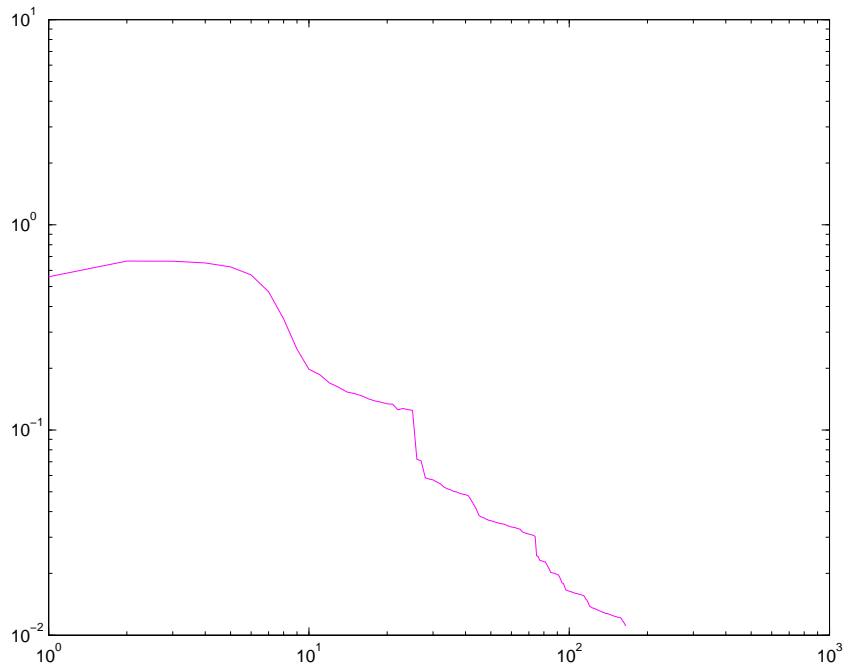
$$\varepsilon = 10^{-3}, \beta = 1, \rho = 0 \text{ and}$$
$$f(x) = \frac{5}{2}\pi \cos\left(\frac{5}{2}\pi x\right)$$

the adaptivity is driven by
the (local) estimator from
below.



the exact solution u .

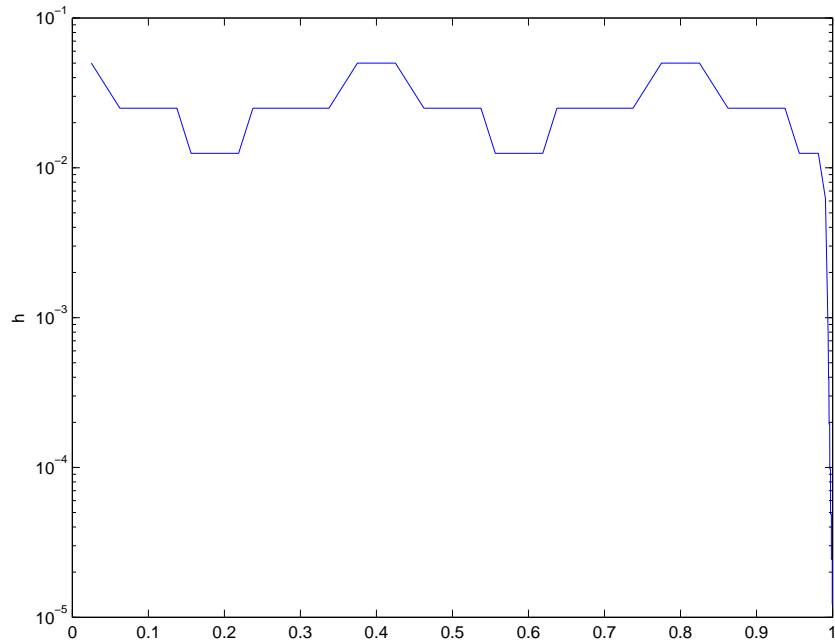
test n.10: error plots



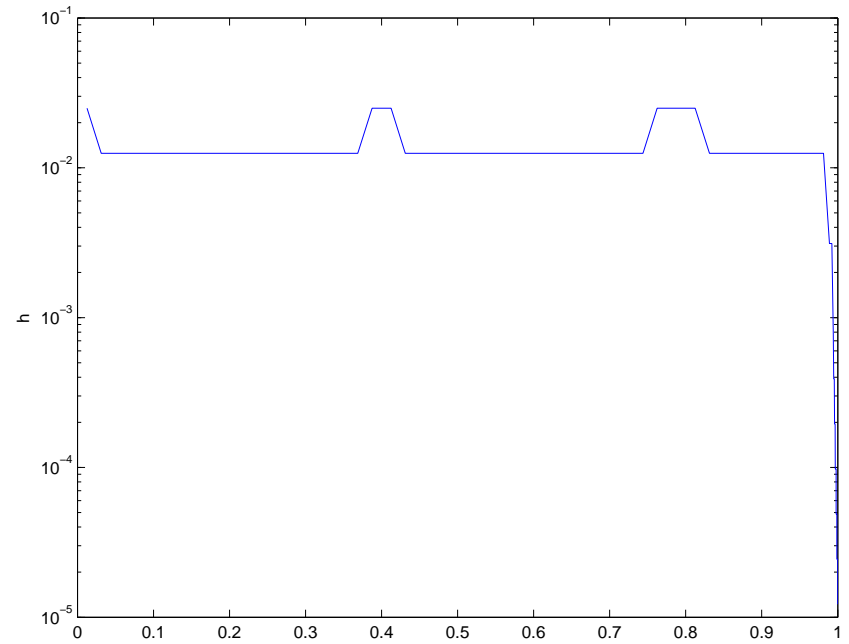
$\|u - u_h\|_E$ vs. the number of d.o.f.;

$\|u - u_h\|_V$, vs. the number of d.o.f..

test n.10: final meshes

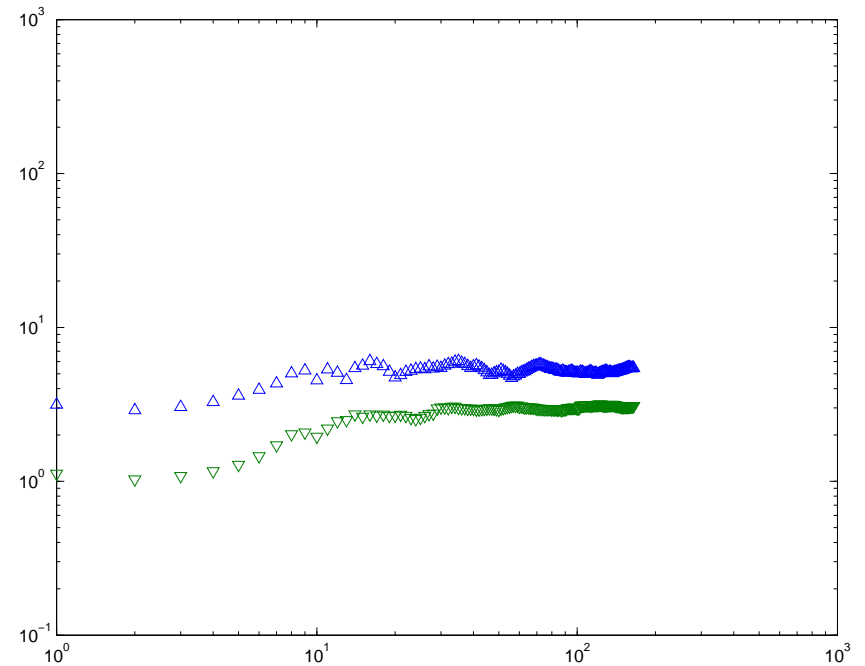
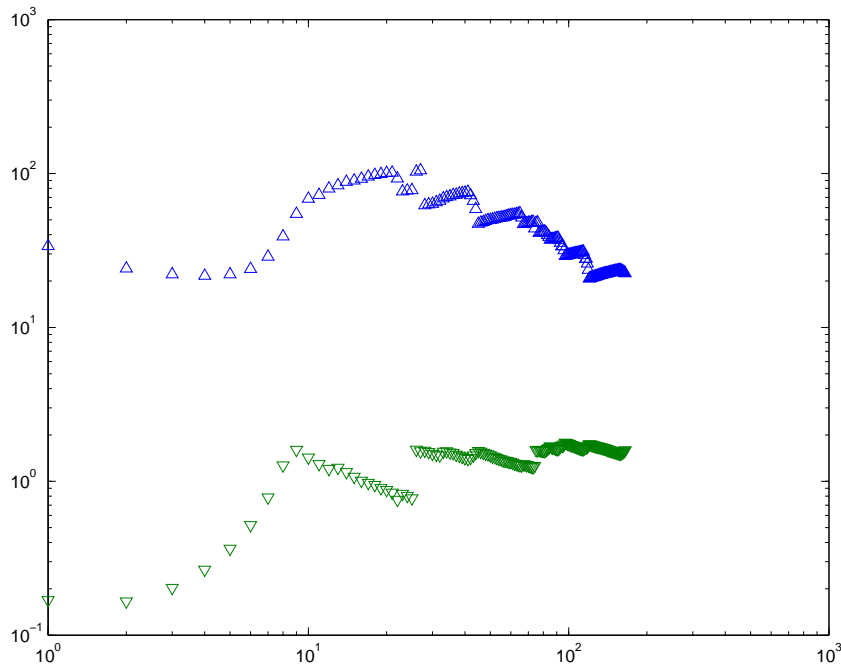


final mesh-sizes using $\check{\eta}_{old}$;



final mesh-sizes using $\check{\eta}_{new}$.

test n.10: effectivity indexes



e.i.: ∇ , $\check{\eta}_{old}$ and \triangle , $\hat{\eta}_{old}$, vs. # d.o.f.; ∇ , $\check{\eta}_{new}$ and \triangle , $\hat{\eta}_{new}$, vs. # d.o.f.